

# Agentic Coding × MOOS-IvP

Introducing the moos-ivp-skills plugin for MOOS-DAWG 2026

## Agentic coding tools

Given a software task, the agent inspects the repository, makes changes, runs the relevant tools, and uses the results to decide what to do next.

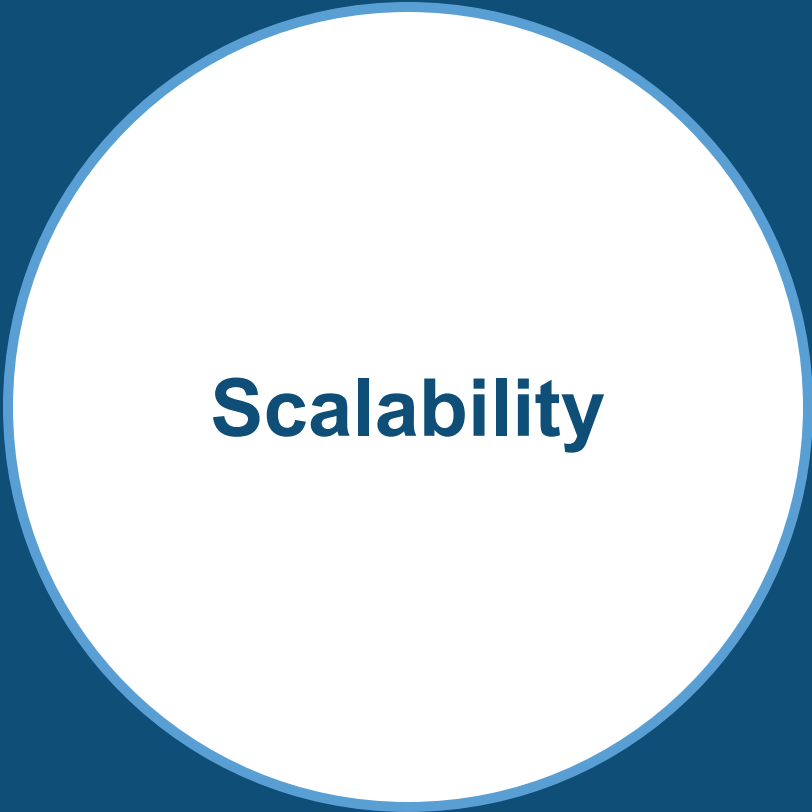
# What guarantees do we need from agentic coding in MOOS-IvP?

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*Agentic coding × MOOS-IvP*



**Accuracy**



**Scalability**

## Two goals

### **Accuracy**

**Does the agent  
understand the  
domain and  
produce a correct  
implementation?**

### **Scalability**

**Can the agent  
produce  
accurate work  
efficiently and  
consistently at  
volume?**

# What is a skill?

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## Purpose

- Specialized guidance for a recurring class of work.

## Selection

- Chosen automatically from the task or invoked explicitly by name.

## Examples

- Build an app. Assemble a mission. Analyze a log.

# How a skill is packaged

Each skill is a folder built around SKILL.md.

## **skill-name/**



|                    |                                              |
|--------------------|----------------------------------------------|
| <b>SKILL.md</b>    | when to use the skill and how to do the work |
| <b>references/</b> | detailed context and examples                |
| <b>scripts/</b>    | repeatable checks and operations             |
| <b>assets/</b>     | templates and baselines                      |

# Long-form article

[Read the companion article →](#)

[Open the MOOS-DAWG talk page →](#)

# App Builder: The Canonical Example

app-builder



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## What it owns

- Builds custom MOOS apps
- Project CMake wiring, AppCasting, accurate documentation, usable ProcessConfig example.
- Uses Mission Builder and Alog Analysis to validate in live launch

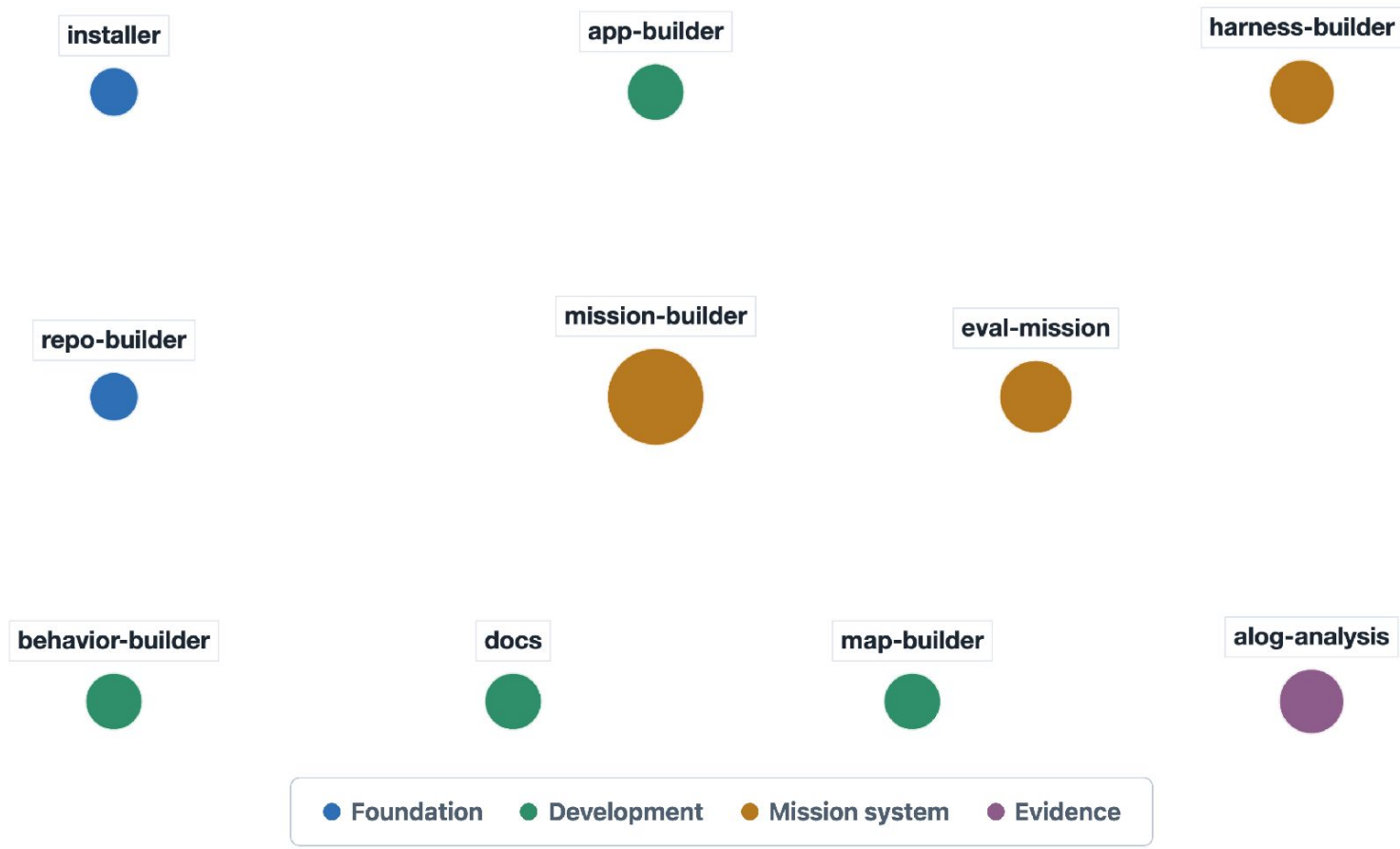
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## Inside the skill package

- **references/** build and CMake wiring upstream examples and app patterns
- **assets/** shared plugin artwork
- **agents/** client presentation metadata

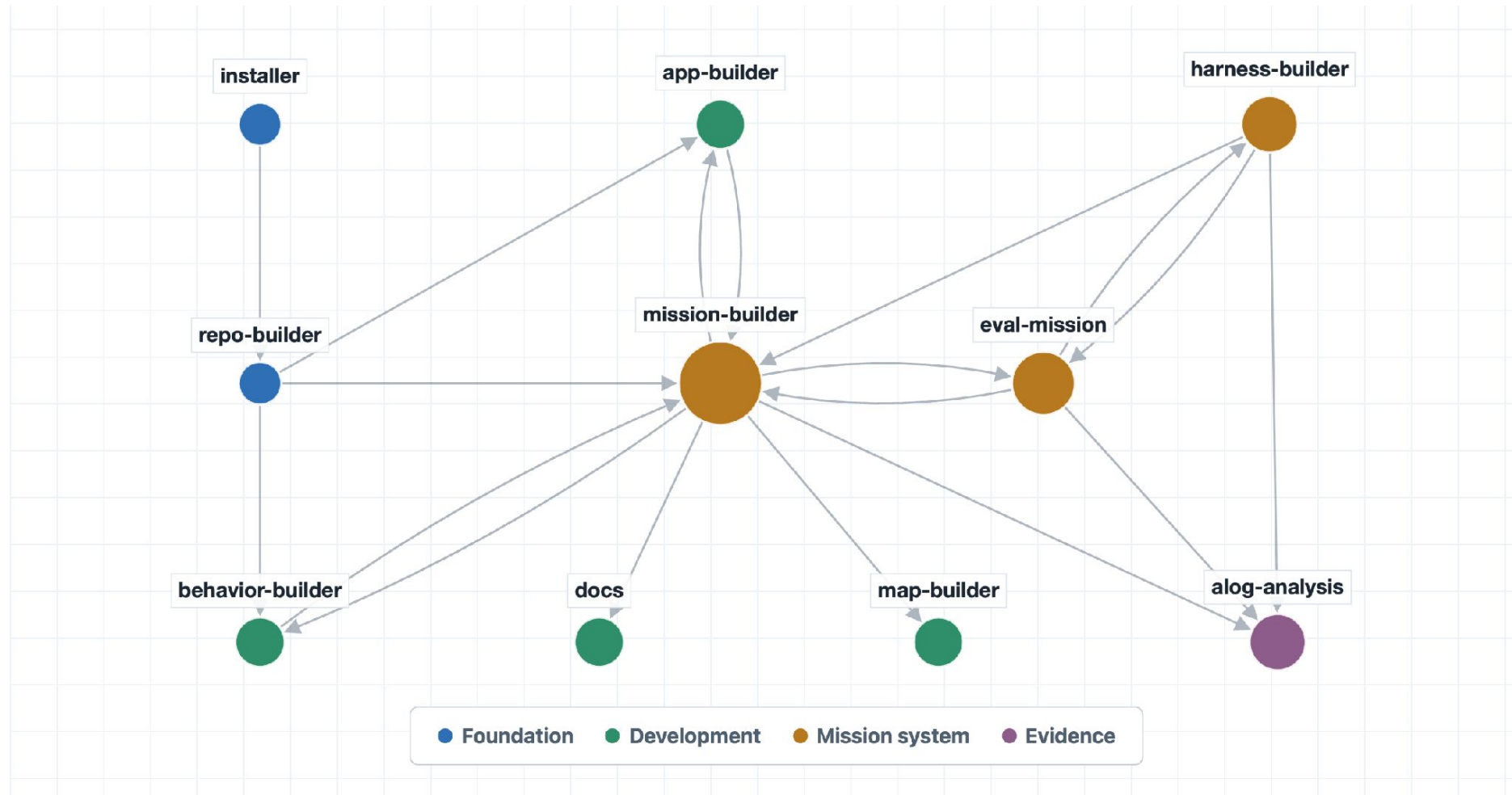
# Ten skills so far

The plugin currently contains ten skills, with more expected as the project matures. Each owns a distinct part of the developer experience. No calls are shown yet.



# Direct handoffs

An arrow marks a deliberate handoff of work or evidence. Mission Builder can consult Docs, use App or Behavior Builder when new software is needed, and pass runtime evidence to ALog Analysis.



# Ten skills, one system

Each skill owns one part of the developer experience—and can call adjacent expertise when needed.

# What's ahead

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## Skills

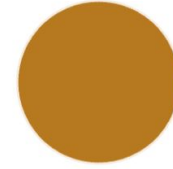
- What does each specialized workflow **own**?

## System design

- How do boundaries, layers, handoffs, and **local customization** keep the system coherent?

## Validation + practice

- How are skills tested with fresh agents—and improved through **real projects**?



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## What it owns

- Builds complete MOOS-IvP missions that people can run and modify
- Sets up vehicle(s), shoreside, behaviors, networking, and visualization
- Checks both the generated files and the live mission

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## Inside the skill package

- **references/** bundled single- and two-vehicle baselines mission style and layered validation
- **scripts/** networking, port, and structural checks
- **assets/** shared plugin artwork
- **agents/** client presentation metadata



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## What it owns

- Documentation-backed answers about MOOS-IvP apps, behaviors, and architecture.
- Prefers oceanai documentation first then local ivp/src source by default
- Can flag differences between documentation and local implementation

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## Inside the skill package

- **references/** manual selection and source fallback
- **assets/** shared plugin artwork
- **agents/** client presentation metadata

# App Builder

app-builder



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## What it owns

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## Inside the skill package

- **references/** build and CMake wiring upstream examples and app patterns
- **assets/** shared plugin artwork
- **agents/** client presentation metadata



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## What it owns

- Builds custom IvP behaviors
- Prefers the simplest behavior form that matches the effect, from posting-only logic through coupled objective functions
- Verifies the full path: build, export, and live pHelmlvP loading

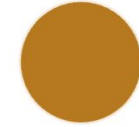
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## Inside the skill package

- **references/** build, lifecycle, and examples IvP-function selection patterns
- **assets/** shared plugin artwork
- **agents/** client presentation metadata

# Eval Mission Builder

eval-mission



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## What it owns

- Adds single-run functionality to an ordinary mission while preserving manual operation.
- Runs headlessly and writes a parseable results.txt.
- pAutoPoke, pMissionEval, uMayFinish

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## Inside the skill package

- **references/** grading, style, automation, validation
- **scripts/** static and isolated live checks
- **assets/** project-scoped teardown helper
- **agents/** client presentation metadata

# Harness Builder

harness-builder



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## What it owns

- Runs a self-evaluating stem mission across a documented matrix of named cases
- Rolling parallel execution
- `-case` `-jobs` `-port_base` `-port_stride` `-keep_workdirs`  
`-gui` default optionality per harness

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## Inside the skill package

- **references/** case matrices, patches, ports, parallelism
- **scripts/** harness contract and static checks
- **assets/** project-scoped teardown helper
- **agents/** client presentation metadata



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## What it owns

- Reconstructs missions and investigates incidents directly from original MOOS .alog files.
- Decides variables worth inspecting, uses aloggrep, aloghelm, alogscan
- Produces timestamped evidence to supplement broader conclusions

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## Inside the skill package

- **references/** tool selection and evidence workflow
- **scripts/** compact variable discovery
- **assets/** shared plugin artwork
- **agents/** client presentation metadata

# Map Builder

map-builder



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## What it owns

- Creates verified MOOS-IvP TIFF background-map bundles through a visual GUI or coordinate-driven CLI
- Preserves bounds, imagery source, zoom, mission origin, output paths, and verification evidence
- Uses one public implementation for both interfaces: [moos-map on PyPI](#).
- Inspired by Conlan Cesar's [AnaxiMap](#) and Raymond Turrisi's non-public prototype

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## Inside the skill package

- **assets/** shared plugin artwork
- **agents/** client presentation metadata

# Repo Builder

repo-builder



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## What it owns

- Creates an independent, user-owned extension repository from the [official moos-ivp-extend template](#)
- Wires the local dependency, build, executable path, behavior-library path, project identity, and fresh Git history
- Consolidates earlier organizational drift around one universal template in the moos-ivp GitHub organization

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## Inside the skill package

- **assets/** shared plugin artwork
- **agents/** client presentation metadata

# Installer

installer



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## What it owns

- Locates or installs the [upstream MOOS-IvP checkout](#) and follows its platform-specific setup instructions
- Creates a small environment file that exposes the core binaries, scripts, and checkout root
- Expected to be the least used skill, but still addresses a common friction point

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## Inside the skill package

- **scripts/** installation validator
- **assets/** shared plugin artwork
- **agents/** client presentation metadata

# Customizing a skill

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Bundled skills suggest useful defaults and can follow references or style requested in a prompt. When a repository needs persistent rules that differ from those defaults, it can provide a [project-local skill](#) without forking the complete plugin.

**1 Use the bundled defaults  
or name a reference and style**

**2 Add a same-name local skill  
for persistent project rules**

**3 The bundled workflow stays  
available by its qualified name**

# Sandboxed agent evaluations

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## Test the guidance

- A main agent creates a clean sandbox and gives a fresh subagent only the skill and a realistic user task.
- The task describes the goal—not a checklist that coaches the agent through the workflow.
- The report includes the artifact, supporting evidence, and the agent's stated approach and key decisions.

## Revise from evidence

- The grader asks whether the result works and whether the skill enabled the agent to reach it independently.
- The author decides whether a failure came from execution or from a reasonable but wrong reading of the guidance.
- If the guidance is at fault, revise it and rerun the task with a fresh agent.

# Skills in practice

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## Developer tooling

- [CI/CD pipeline](#)
- [MOOS-IvP VS Code extension](#)
- [Headless missions-auto debugging](#)

## Research + field work

- Master's thesis harnesses
- [PEARL development](#)
- [KONGSBERG Coastal Monitoring](#)

## Education

- [MOOS-IvP NotebookLM TA](#)
- Greece minicourse

# MOOS-IvP CI/CD

Local and automated regression testing for MOOS-IvP applications, behaviors, and missions. Focused CTests are paired with complete headless mission harnesses.

[GitHub repository](#)

[Project site](#)

CI MOOS-IvP CI/CD

Quick Start Harnesses Unit Tests Examples

## CI/CD Pipeline for MOOS-IvP Apps, Behaviors, and Libraries

C++ unit tests check individual classes and functions, while mission harnesses test live MOOS processes, vehicle motion, and system-level outcomes.

Developer quick start Harnesses Unit Tests Examples

REPOSITORY SNAPSHOT

| Matrix: runtime-harnesses       |        |
|---------------------------------|--------|
| runtime / collision_h01 ...     | 1m 12s |
| runtime / convoy_h01 / ...      | 9m 7s  |
| runtime / fixedturn_h0... / ... | 1m 55s |
| runtime / loiter_h01 / H...     | 4m 18s |
| runtime / obstacle_beh...       | 1m 54s |
| runtime / oregion_h0...         | 2m 30s |
| runtime / shadow_h01 / ...      | 5m 47s |
| runtime / stationkeep...        | 4m 47s |
| runtime / trail_h01 / H0...     | 7m 28s |
| runtime / waypoint_h0...        | 4m 38s |

# MOOS-IvP VS Code

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The editor extension goes beyond syntax highlighting with hover documentation, folding, formatting, definitions, and conservative diagnostics for mission, behavior, and patch files.

[GitHub repository](#)

```
ProcessConfig = pHelmIvP
{
    AppTick    = 4 // Quick Fix should preserve this comment
    CommsTick  = 4

    verbose    = true
    behaviors  = meta_vehicle.bhv
}

ProcessConfig = pMarineViewer
{
    AppTick    = 4
    CommsTick  = 4
    tiff_file   = viewer_back.tif

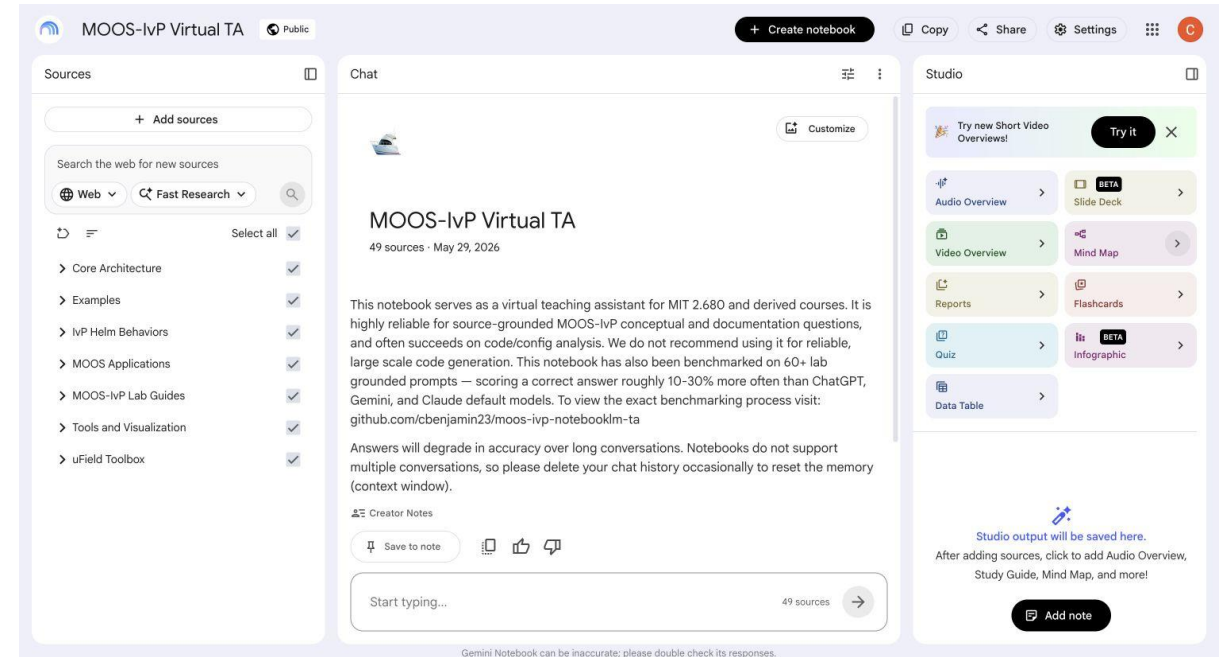
    // Full-line comments keep their text, but indentation is normalized.
    left_context = x=0,y=0,scale=1.0
}
```

# MOOS-IvP-TA

**A documentation-grounded NotebookLM teaching assistant for MIT 2.680 labs, backed by 49 curated sources and benchmarking checked against MOOS-IvP source.**

[Open the notebook](#)

[GitHub repository](#)



# Commit activity

**92 commits across 22 active days.**

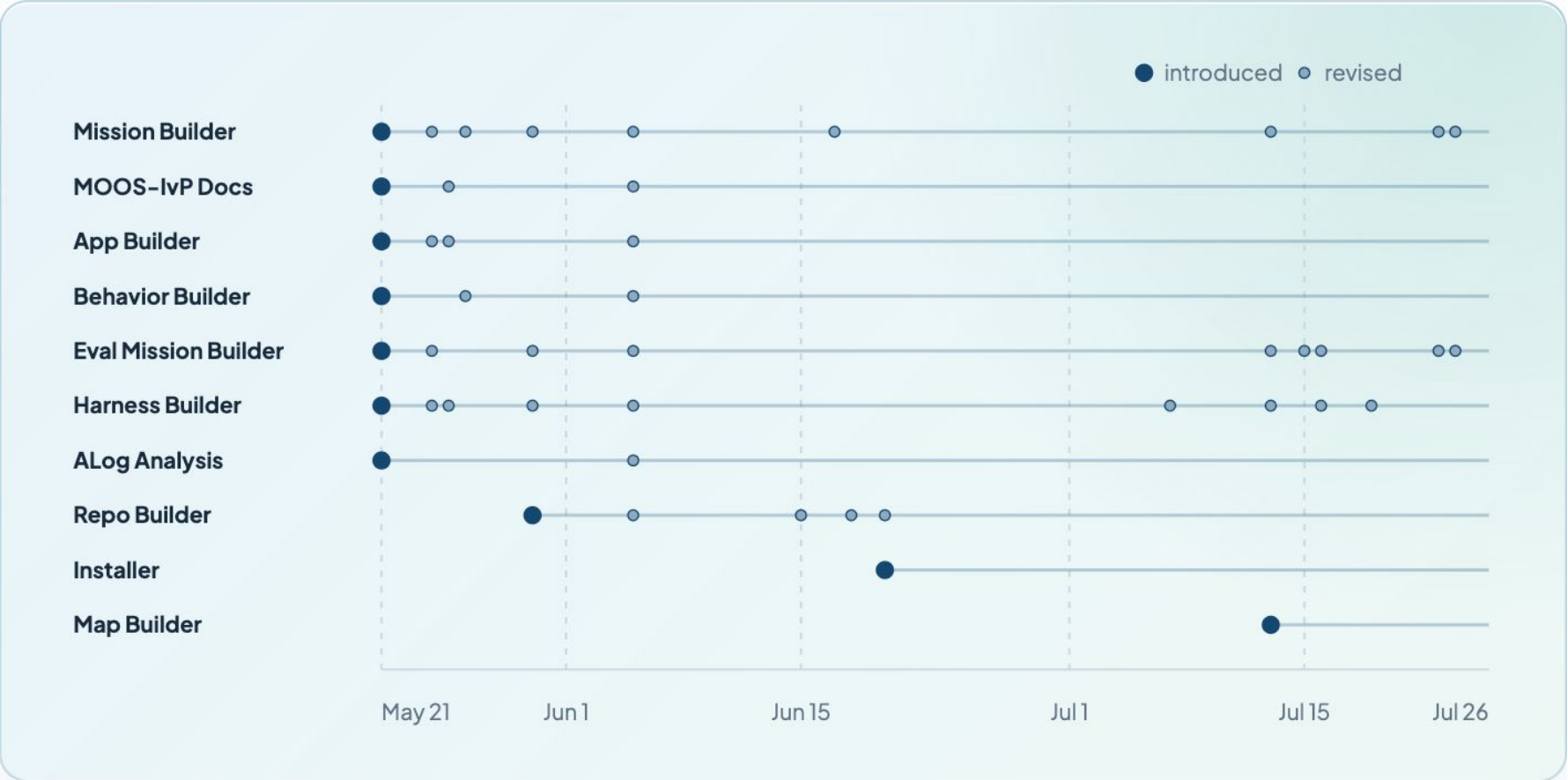
**The wave shows the concentrated periods in which the skills, supporting material, and validation workflows were assembled and revised.**



# Skill evolution

Large markers show when a skill entered the plugin. Smaller markers show later revisions to its guidance or supporting material.

Branding-only changes are excluded.



# Takeaways

- Accuracy + Scalability
- Customizable
- Validation MOAT
- Encourage Use

# Questions?

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## MOOS-IvP-Skills

[github.com/cbenjamin23/moos-ivp-skills](https://github.com/cbenjamin23/moos-ivp-skills)

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